

Use of a Radial Turbine in a Thrust Augmentation Scheme

RONALD J. WILLS* AND BARRY S. SEIDEL†

University of Delaware, Newark, Del.

AND

ROBERT B. COTTON‡

Wedge Company Inc., Media, Pa.

Theme

A thrust augmentation scheme, for use in launching jet aircraft is analyzed. The proposal utilizes aircraft exhaust kinetic energy to drive a radial turbine.

Contents

The system proposed¹ is portrayed in Fig. 1. It utilizes a partial admission, radial inflow impulse turbine placed in the exhaust of a jet engine. The torque developed by the turbine is used to wrap up, on a capstan, a cable, which may be fixed at some distant point down the runway. The turbine-capstan is mounted on a wheeled platform so that it tends to follow the jet down the runway. A rigid member connects the platform to the turbojet, allegedly exerting an additional thrust.

The equation of motion of the system may be analyzed

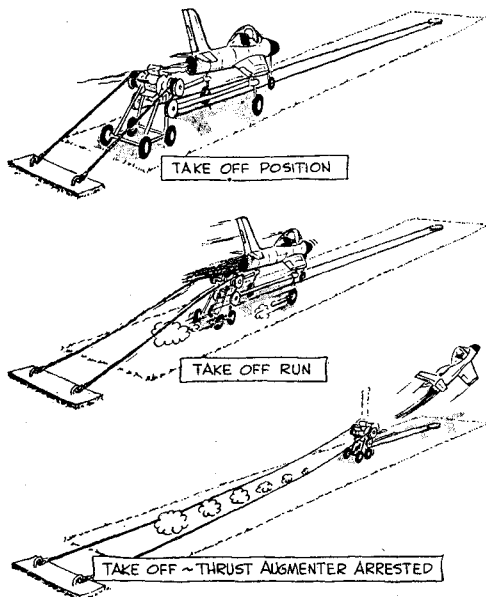


Fig. 1 Thrust augmentser—sequence of operation.

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* Research Fellow.

† Professor of Mechanical and Aerospace Engineering. Associate Fellow AIAA.

‡ President. Member AIAA.

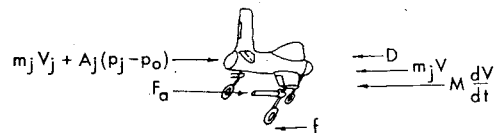
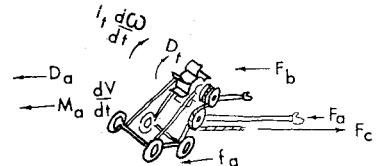


Fig. 2 Forces acting on augmentser and on aircraft.

with the aid of Fig. 2. For the augmentser, we have

$$M_a(dV/dt) = F_c - F_a - F_{bx} - D_a - f_a \quad (1)$$

where M , V , F , D , f are respectively; mass, velocity, force, drag, friction force. Subscripts a , c , b are respectively; augmentser, cable, and blade. Note that F_b is the vector blade force, and F_{bx} is its component in the horizontal (x) direction. For the aircraft, we have

$$M dV/dt = F_a + m_j V_j + A_j(p_j - p_o) - m_j V - D - f \quad (2)$$

Here m_j , A , and p are respectively; mass flow, area, and pressure. Subscript j refers to the jet. In Eq. (2), we may identify the engine net thrust

$$F_n = m_j V_j + A_j(p_j - p_o) - m_j V \quad (3)$$

Adding Eq. (1) and (2) gives

$$(M + M_a)(dV/dt) = F_n - (D + D_a) - (f + f_a) + (F_c - F_{bx}) \quad (4)$$

Again referring to Fig. 2, angular momentum considerations yield

$$I_t(d\omega/dt) = (F_{b\theta} - D_t)R_t - F_c R_d \quad (5)$$

I_t is the turbine moment of inertia, R is radius, R_d is the drive (capstan) radius, θ refers to tangential component. Eq. (5) may be solved for F_c , and the result used in Eq. (4). Additionally, we introduce x , the distance the system travels. Then

$$V = (dx/dt), \omega R_d = \dot{x} \quad \text{and} \quad \dot{\omega} R_d = \ddot{x}$$

Writing the drag and friction force in terms of coefficients $D = \frac{1}{2}\rho\dot{x}^2 A C_D$, $D_a = \frac{1}{2}\rho\dot{x}^2 A_a C_{Da}$, $f = \mu M$, $f_a = \mu M_a$. Eq. 4 may now be expressed as

$$\left(M + M_a + \frac{I_t}{R_d^2}\right)\ddot{x} = m_j V_j + A_j(p_j - p_o) -$$

$$m_j \dot{x} - \frac{1}{2}\rho\dot{x}^2(A C_D + A_a C_{Da}) - \mu(M + M_a) + (F_{b\theta} - D_t) \times \frac{R_t}{R_d} - F_{bx} \quad (6)$$

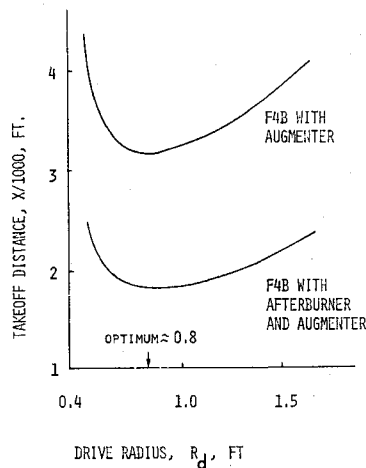


Fig. 3 F-4B takeoff distance as a function of capstan radius.

Table 1 Acceleration characteristics, $R_d = 0.8$ ft

Vel. fps	With augmenter		Without augmenter	
	Max. A/B	Non-A/B	Max. A/B	Non-A/B
	Ground distance, x ft			
100	150	210	270	440
200	610	1100	1210	2150
300	1850	3150	3300	6700
	Acceleration force, $M\ddot{x}$, lbs			
100	58,500	37,300	31,700	18,600
200	47,000	28,800	26,000	14,000
300	31,500	16,200	20,000	7900

$F_{b\theta}$, F_{bx} , and D_t may be determined as a function of ω (and hence \dot{x}) by simply testing a turbine (with attached dynamometer) or (approximately) by analysis. This second-order equation may then be solved numerically, i.e., by Euler's method.

Tests were conducted on a variety of turbines, always seeking those having large values of $(F_{b\theta} - D_t)/F_{bx}$. An analysis was also performed.

If the (scaled) characteristics of the best turbine tested, data for the F-4B aircraft, a choice for R_t/R_d , and assumptions for the other parameters are introduced into Eq. (6), we may compute $x(t)$, $\dot{x}(t)$, $\ddot{x}(t)$. It turns out that there is an optimum drive radius, that is, a radius which yields the minimum take-

off distance for an assigned takeoff velocity as shown in Fig. 3. It can be seen that decreasing the drive radius will increase the ratio R_t/R_d and hence the blade load term in Eq. (6). However, this increase in R_t/R_d also results in an increase in the maximum speed of the turbine and hence a greater drag.

Table 1 illustrates how ground accelerations of the F-4B would improve by application of this augmentation scheme. For a takeoff velocity of, say, 300 fps the ground roll is reduced to about half of the normal distance without augmentation.

Reference

- ¹ *Thrust Augmenter Means*, U.S. Patent Office, Patent 3,400,903 Sept. 10, 1968, assigned to R. B. Cotton, Media, Pa.